

# MA 225-002 Test 3 Definitions

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$A \times B = \{(a, b) : a \in A \text{ and } b \in B\}$ .

A *relation* from  $A$  to  $B$  is a subset  $R$  of  $A \times B$ . We say that  $a$  is *R-related* to  $b$ , and write  $a R b$ , if  $(a, b) \in R$ .

A relation from  $A$  to  $A$  is usually just called a relation *on*  $A$ .

Let  $A$  be a set and let  $R$  be a relation on  $A$ .

1.  $R$  is *reflexive* if for all  $x \in A$ ,  $x R x$ .
2.  $R$  is *symmetric* if for all  $x$  and  $y$  in  $A$ , if  $x R y$ , then  $y R x$ .
3.  $R$  is *transitive* if for all  $x$ ,  $y$  and  $z$  in  $A$ , if  $x R y$  and  $y R z$ , then  $x R z$ .

A relation  $R$  on a set  $A$  is an *equivalence relation* if  $R$  is reflexive, symmetric and transitive.

Let  $R$  be an equivalence relation on  $A$  and let  $x \in A$ . The *equivalence class* of  $x$  is

$$[x] = \{y \in A : x R y\}.$$

$[x]$  is also written  $x/R$ .

Let  $m$  be a positive integer. The relation  $\equiv_m$  on  $\mathbb{Z}$  is defined by

$$x \equiv_m y \text{ if } m \text{ divides } x - y.$$

The set of equivalence classes for  $\equiv_m$  is denoted  $\mathbb{Z}_m$ , which is pronounced “ $\mathbb{Z}$  mod  $m$ .” It has  $m$  elements:  $[0], [1], \dots, [m - 1]$ .

A function  $f$  from  $A$  to  $B$  is a relation from  $A$  to  $B$  that satisfies

1. For each  $x \in A$  there exists  $y \in B$  such that  $x f y$ .
2. If  $x f y$  and  $x f z$  then  $y = z$ .

A function  $f$  from  $A$  to  $B$  is usually denoted  $f : A \rightarrow B$ . We always write  $f(x) = y$  to mean  $x f y$ .  $A$  is called the *domain* of  $f$ , and  $B$  is called the *codomain* of  $f$ . Condition (2) says that functions are well-defined: There is no ambiguity in which element of  $B$  is  $f(x)$ . Condition (1) says that  $f(x)$  is defined for every  $x \in A$ .

The *range* of  $f$  is  $\{y \in B : \text{there exists } x \in A \text{ such that } f(x) = y\}$ .

Common functions:

1. The *identity function* on  $A$ :  $I_A : A \rightarrow A$ ,  $I_A(x) = x$ .
2. For  $A \subseteq B$ , the *inclusion map* from  $A$  to  $B$ :  $i : A \rightarrow B$ ,  $i(x) = x$ .
3. The *projections* of  $A \times B$  onto  $A$  and  $B$ :  $\Pi_1 : A \times B \rightarrow A$ ,  $\Pi_1(x, y) = x$ , and  $\Pi_2 : A \times B \rightarrow B$ ,  $\Pi_2(x, y) = y$ .

Two functions  $f$  and  $g$  are *equal* if

1. They have the same domain  $A$ .
2. For all  $x \in A$ ,  $f(x) = g(x)$ .

Our text does not require that the codomains be the same.

If  $f : A \rightarrow B$  and  $D \subseteq A$ , the *restriction of  $f$  to  $D$*  is denoted  $f|_D$  and is defined as follows:  $f|_D : D \rightarrow B$ ,  $f|_D(x) = f(x)$ .

Let  $f : A \rightarrow B$  and  $g : B \rightarrow C$  be functions.  $g \circ f : A \rightarrow C$  is defined by  $(g \circ f)(x) = g(f(x))$ .

A function  $f : A \rightarrow B$  is called *surjective* or *onto* if the range of  $f$  is  $B$ . In other words,  $f$  is onto if for each  $y \in B$  there exists  $x \in A$  such that  $f(x) = y$ .

A function  $f : A \rightarrow B$  is called *injective* or *one-to-one* if for all  $x_1, x_2 \in A$ , if  $x_1 \neq x_2$ , then  $f(x_1) \neq f(x_2)$ . Equivalently,  $f$  is one-to-one if for all  $x_1, x_2 \in A$ , if  $f(x_1) = f(x_2)$ , then  $x_1 = x_2$ .

If  $f : A \rightarrow B$  is called a *bijection* if it is one-to-one and onto. In this case one can define its inverse function  $f^{-1} : B \rightarrow A$  as follows:  $f^{-1}(y) = x$  if and only if  $y = f(x)$ .